

# Calibration with Reduced Order Models for PIDEs

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# What's this presentation about?

**goal:** calibration of option pricing models

- model prices are calculated via a partial (integro) differential equation

**problem:** no closed-form solution for many of these problems

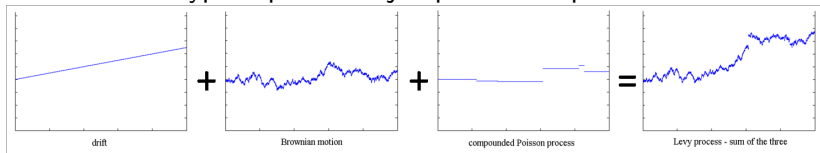
- a numerical solution is required
- multiple solution of large-scaled linear systems of equations (LSE)
- calibration problems are very time expensive

**solution:** Proper Orthogonal Decomposition (POD)

- save computing time during the repeated solution of the LSE's

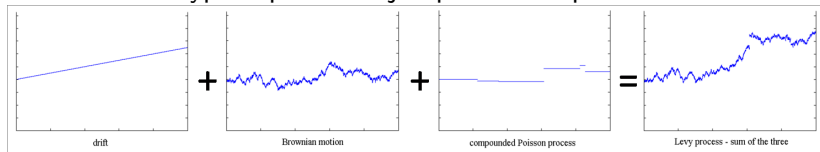
# Pricing european options in jump diffusion models

Typical path of a jump diffusion process



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Typical path of a jump diffusion process



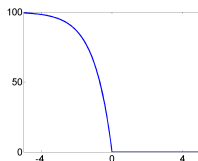
Log-transformed PIDE of a general jump diffusion model

$$\begin{aligned}
 D_T(x, T) - \frac{\sigma^2(x, T)}{2} D_{xx}(x, T) + \left( r(T) + \frac{\sigma^2(x, T)}{2} - \lambda \zeta \right) D_x(x, T) + \\
 + \lambda(1 + \zeta) D(x, T) - \lambda \int_{-\infty}^{+\infty} D(x - y, T) e^y f(y) dy = 0 \\
 \text{on } (-\infty, \infty) \times (0, T_{max})
 \end{aligned}$$

with initial condition  $D(x, 0) = \max\{S_0 - S_0 e^x, 0\}$ .

## Problem: Integrability of the initial condition

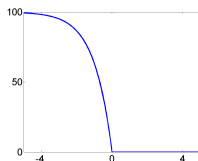
$$D(x, 0) = \max\{S_0 - S_0 e^x, 0\} =: D_0(x)$$
$$D_0(x) \xrightarrow{x \rightarrow -\infty} S_0 \Rightarrow \text{not } L^2(\mathbf{R})\text{-integrable}$$



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$$D_0(x) \xrightarrow{x \rightarrow -\infty} S_0 \Rightarrow \text{not } L^2(\mathbf{R})\text{-integrable}$$



### Weighted function spaces ( $\mu \in \mathbf{R}$ )

$$L^2_{-\mu}(\mathbf{R}) := \left\{ v \in L^1_{loc}(\mathbf{R}) : v(\cdot)e^{-\mu|\cdot|} \in L^2(\mathbf{R}) \right\}$$

with  $\langle v, w \rangle_{L^2_{-\mu}} := \int_{\mathbf{R}} v(x)w(x)e^{-2\mu|x|} dx$  a Hilbert space.

$$H^1_{-\mu}(\mathbf{R}) := \left\{ v \in L^1_{loc}(\mathbf{R}) : v(\cdot)e^{-\mu|\cdot|}, v'(\cdot)e^{-\mu|\cdot|} \in L^2(\mathbf{R}) \right\}$$

with  $\langle v, w \rangle_{H^1_{-\mu}} := \langle v, w \rangle_{L^2_{-\mu}} + \langle v', w' \rangle_{L^2_{-\mu}}$  a Hilbert space, too.

# Variational formulation

With an appropriate bilinear form

$$a^{-\mu}(\cdot; \cdot, \cdot) : [0, T_{max}] \times \left( H_{-\mu}^1(\mathbf{R}) \times H_{-\mu}^1(\mathbf{R}) \right) \rightarrow \mathbf{R}$$

we get the variational formulation:

## Problem

Find  $D \in W([0, T_{max}], H_{-\mu}^1(\mathbf{R}))$  with

$$\left\langle D_T(\cdot, T), w(\cdot) \right\rangle_{L_{-\mu}^2} + a^{-\mu} \left( T; D(\cdot, T), w(\cdot) \right) = 0 \quad \forall w \in H_{-\mu}^1(\mathbf{R})$$

with initial condition:

$$\left\langle D(\cdot, 0), w(\cdot) \right\rangle_{L_{-\mu}^2} = \left\langle D_0(\cdot), w(\cdot) \right\rangle_{L_{-\mu}^2} \quad \forall w \in H_{-\mu}^1(\mathbf{R})$$

Time dependent bilinear form  $a$ 

$$\begin{aligned} a^{-\mu}(T; v, w) &= \int_{\mathbb{R}} \frac{\sigma^2(x, T)}{2} v'(x) w'(x) e^{-2\mu|x|} dx \\ &+ \int_{\mathbb{R}} \left( r(T) + \frac{\sigma^2(x, T)}{2} - \lambda\zeta + \left( \frac{\sigma(x, T)}{2} \right)_x + \sigma^2(x, T) \cdot \mu \cdot \text{sign}(x) \right) \cdot v'(x) w(x) e^{-2\mu|x|} dx \\ &+ \int_{\mathbb{R}} \lambda(1 + \zeta) v(x) w(x) e^{-2\mu|x|} dx - \lambda \int_{\mathbb{R}} \int_{\mathbb{R}} v(x - y) w(x) e^{-2\mu|x|} e^y f(y) dy dx \end{aligned}$$



Time dependent bilinear form  $a$ 

$$\begin{aligned}
 a^{-\mu}(T; v, w) &= \int_{\mathbb{R}} \frac{\sigma^2(x, T)}{2} v'(x) w'(x) e^{-2\mu|x|} dx \\
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 &+ \int_{\mathbb{R}} \lambda(1 + \zeta) v(x) w(x) e^{-2\mu|x|} dx - \lambda \int_{\mathbb{R}} \int_{\mathbb{R}} v(x - y) w(x) e^{-2\mu|x|} e^y f(y) dy dx
 \end{aligned}$$

Properties of  $a$  ( $\exists c_1, c_2 > 0, c_3 \in \mathbb{R}$ )

$$|a^{-\mu}(T; v, w)| \leq c_1 \cdot \|v\|_{H_{-\mu}^1} \|w\|_{H_{-\mu}^1} \quad \forall T \in [0, T_{\max}]$$

$$a^{-\mu}(T; v, v) \geq c_2 \cdot \|v\|_{H_{-\mu}^1}^2 - c_3 \cdot \|v\|_{L_{-\mu}^2}^2 \quad \forall T \in [0, T_{\max}]$$

## Spatial discretization

$$\mathcal{H}_n \xrightarrow{n \rightarrow \infty} H_{-\mu}^1 \text{ with a finite basis } \{\Phi_i\}_{i=1}^n \\ \Rightarrow \hat{D}(x, T) = \sum_{i=1}^n \alpha_i(T) \Phi_i(x)$$

## Semi-discretized problem

Find  $\alpha_i(\cdot) : (0, T_{max}) \rightarrow \mathbf{R}$ ,  $i = 1, \dots, n$

$$\sum_{i=1}^n \dot{\alpha}_i(T) \langle \Phi_i, \Phi_j \rangle_{L^2_{-\mu}} + \sum_{i=1}^n \alpha_i(T) a^{-\mu}(T; \Phi_i, \Phi_j) = 0$$

with initial condition:

$$\forall j = 1, \dots, n$$

$$\sum_{i=1}^n \alpha_i(0) \langle \Phi_i, \Phi_j \rangle_{L^2_{-\mu}} = \langle D_0(\cdot), \Phi_j \rangle_{L^2_{-\mu}} \quad \forall j = 1, \dots, n$$

# Numerical solution

## Linear system of equations

Find  $\alpha(T_k) \in \mathbf{R}^n \forall k = 0, \dots, m$

$$\begin{aligned} \left( M + \Delta T \cdot \theta \cdot A(T_{k+1}) \right) \cdot \alpha(T_{k+1}) &= \\ &= \left( M - \Delta T \cdot (1 - \theta) \cdot A(T_k) \right) \cdot \alpha(T_k) \end{aligned}$$

with initial condition  $M \cdot \alpha(T_0) = B$

- $\theta = 0$ : explicit Euler method
- $\theta = 0.5$ : Crank-Nicolson method
- $\theta = 1$ : implicit Euler method
  
- $M$  sparse mass matrix
- $A(T)$  stiffness matrix (dense due to the integral term)

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- 3 Calibration

# Proper Orthogonal Decomposition

What is POD?

**Given:** Functions/vectors  $u_1, \dots, u_n$  ( $\Rightarrow$  Snapshots)

$\mathcal{V} := \text{span}\{u_1, \dots, u_n\}$  with  $\text{rg}(\mathcal{V}) = r \leq n$

**Find:** Orthonormal basis function/vectors  $\Psi_1, \dots, \Psi_p$  (with  $p \leq r$ )

with which an „average“ function  $v \in \mathcal{V}$  can be described at the best

$\Rightarrow$  Extract significant information from given data

# Illustration

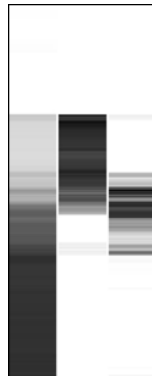


Holiday picture

# Illustration

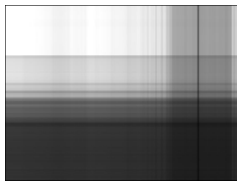
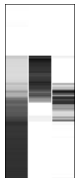


Holiday picture



Extract  
significant  
information

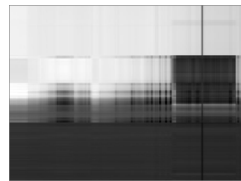
# Illustration



1 basis function



2 basis functions



3 basis functions



10 basis functions



20 basis functions



50 basis functions



## Definition

Let „snapshots“  $u_1, \dots, u_n \in H$  be given.

## POD basis

Find orthonormal vectors  $\Psi_1, \dots, \Psi_r \in \text{span}(u_1, \dots, u_n)$ , solving:

$$\min_{\Psi_1, \dots, \Psi_p} \sum_{i=1}^n \gamma_i \left\| u_i - \sum_{j=1}^p \langle u_i, \Psi_j \rangle_H \Psi_j \right\|_H^2$$
$$\text{s.t. } \langle \Psi_k, \Psi_l \rangle_H = \delta_{kl} \quad \forall k, l = 1, \dots, p$$

for all  $p \in \{1, \dots, r\}$  and weighting factors  $\gamma_i > 0$ ,  $i = 1, \dots, n$ .

e.g.  $\gamma_i = \frac{1}{n}$  for the arithmetic mean.

# Calculation of the basis functions

## Sufficient optimality condition

Define  $\mathcal{R} \in \mathcal{L}(H, H)$  with  $\mathcal{R}z := \sum_{i=1}^n \gamma_i \langle z, u_i \rangle_H u_i$

Then there exists a complete orthonormal basis  $\{\Psi_k\}_{k \geq 1}$  and a sequence of non-negative real numbers  $\{\lambda_k\}_{k \geq 1}$  with

$$\mathcal{R}\Psi_k = \lambda_k \Psi_k \quad \text{mit } \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r > 0 \text{ und } \lambda_j = 0 \quad \forall j > r$$

The eigenvectors  $\Psi_k$  solve the minimization problem above.

The eigenvectors corresponding to the  $p$  largest eigenvalues, build the POD basis of rank  $p$ .

# Using POD to solve the PIDE

- 1 Snapshots:  $D(x, T_k) \in \mathcal{H}_n$  ( $k = 0, \dots, m$ ) from a known solution
- 2 Calculate the POD basis  $\{\Psi_i\}_{i=1}^p$  with rank  $p$   
(by solving the eigenvalue problem)  
 $\Rightarrow \exists \beta(T_k)$  with  $D(x, T_k) \approx \sum_{i=1}^p \beta(T_k) \Psi_i(x)$
- 3 Use  $\{\Psi_i\}_{i=1}^p$  instead of the FE basis functions

Reminder: Discretization in  $x$  direction

$$\mathcal{H}_n \text{ with basis } \{\Phi_i\}_{i=1}^n \\ \Rightarrow D(x, T) = \sum_{i=1}^n \alpha_i(T) \Phi_i(x)$$

## Semi discretized problem

Find  $\alpha_i(\cdot) : (0, T_{max}) \rightarrow \mathbf{R}$ ,  $i = 1, \dots, n$ , where

$$\sum_{i=1}^n \dot{\alpha}_i(T) \langle \Phi_i, \Phi_j \rangle_{L^2_{-\mu}} + \sum_{i=1}^n \alpha_i(T) a^{-\mu}(T; \Phi_i, \Phi_j) = 0$$

with initial condition:

$$\forall j = 1, \dots, n$$

$$\sum_{i=1}^n \alpha_i(0) \langle \Phi_i, \Phi_j \rangle_{L^2_{-\mu}} = \langle D_0(\cdot), \Phi_j \rangle_{L^2_{-\mu}} \quad \forall j = 1, \dots, n$$

Discretization in  $x$  direction using the POD basis

$$\mathcal{V}^p \text{ with basis } \{\Psi_i\}_{i=1}^p \\ \Rightarrow D^{POD}(x, T) = \sum_{i=1}^p \alpha_{POD,i}(T) \Psi_i(x)$$

## Semi discretized problem

Find  $\alpha_{POD,i}(\cdot) : (0, T_{max}) \rightarrow \mathbf{R}$ ,  $i = 1, \dots, p$ , where

$$\sum_{i=1}^p \dot{\alpha}_{POD,i}(T) \langle \Psi_i, \Psi_j \rangle_{L^2_{-\mu}} + \sum_{i=1}^p \alpha_{POD,i}(T) a^{-\mu}(T; \Psi_i, \Psi_j) = 0$$

with initial condition:

$$\forall j = 1, \dots, p$$

$$\sum_{i=1}^p \alpha_{POD,i}(0) \langle \Psi_i, \Psi_j \rangle_{L^2_{-\mu}} = \langle D_0(\cdot), \Psi_j \rangle_{L^2_{-\mu}} \quad \forall j = 1, \dots, p$$

## Comparison POD vs. FEM

For each time step  $T_k$  - i.e.  $m$  times - a linear system of equations has to be solved:

- FEM** LSE on the scale of  $n \times n$   
( $n$ : number of discretization steps in  $x$  direction)
- POD** LSE on the scale of  $p \times p$   
( $p$ : number of POD basis functions)  
where  $p \ll n$

# Comparison POD vs. FEM

Use FEM solution  $u_1^{FEM}(x), \dots, u_n^{FEM}(x)$  as snapshots to build a POD basis  $u_1^{POD}(x), \dots, u_n^{POD}(x)$  the solution of the corresponding POD system.

## Error estimation

### 1 Implicit Euler

$$\frac{1}{n} \sum_{i=1}^n \left\| u_i^{FEM} - u_i^{POD} \right\|_H^2 \leq \bar{C}_1 \sum_{j=p+1}^r \lambda_j$$

### 2 Crank-Nicolson method, with $\Delta t < \sqrt[3]{\frac{16\kappa}{c_{ip}^2 \alpha \|S\|_2^2}}$

$$\frac{1}{n} \sum_{i=1}^n \left\| u_i^{FEM} - u_i^{POD} \right\|_H^2 \leq \tilde{C}_1 \sum_{j=p+1}^r \lambda_j$$

## Comparison POD vs. FEM: numerical results

- $\epsilon = \frac{1}{n} \sum_{i=1}^n \left\| u_i^{FEM} - u_i^{POD} \right\|_H^2$ ,  $\lambda_i$  eigenvalues
- $p$  number of POD basis functions

$p$	$\epsilon$	$\sum_{i=p+1}^r \lambda_i$
5	5.95e-002	2.42e+001
6	7.71e-003	3.99e+000
7	9.38e-004	6.35e-001
8	1.12e-004	9.70e-002
9	1.32e-005	1.43e-002
10	1.53e-006	2.02e-003
11	1.74e-007	2.74e-004
12	1.95e-008	3.59e-005



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## Calibration of option pricing models

## Calibration problem (Merton's model)

Find  $(\sigma, \lambda, \mu_J, \sigma_J)$  as a solution of

$$\min_{(\sigma, \lambda, \mu_J, \sigma_J)} \sum_{i=1}^k \left( D((\sigma, \lambda, \mu_J, \sigma_J); x_i, T_i) - C_M^i \right)^2$$

$C_M^i$  given market prices for different options with maturities  $T_i$  and strike prices  $x_i$

$D((\sigma, \lambda, \mu_J, \sigma_J); x_i, T_i)$  corresponding model prices determined by the Dupire PIDE

# Necessity of updates

Rebuild Gauss using information of Gauss



# Necessity of updates

Rebuild Gauss using information of Gauss



Rebuild Newton using information of Gauss



# Necessity of updates

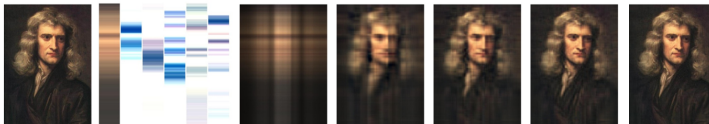
Rebuild Gauss using information of Gauss



Rebuild Newton using information of Gauss



Rebuild Newton using information of Newton

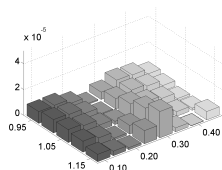


# Trust region updates - Example (Merton's Jump diffusion model)

## Line search algorithm using the FEM solutions:

FEM evaluations: 285 ( $2000 \times 2000$ )

Time overall: 955 sec

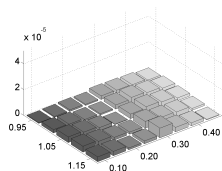


## Trust region POD:

FEM evaluations: 9 ( $2000 \times 2000$ )

POD evaluations: 328

Time overall: 60 sec (FEM: 36 sec, POD: 24 sec)

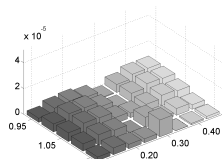


## Multi-level trust region POD:

FEM evaluations: 3 ( $500 \times 500$ ), 2 ( $1000 \times 1000$ ), 5 ( $2000 \times 2000$ )

POD evaluations: 321

Time overall: 42 sec (FEM: 22 sec, POD: 20 sec)



Thank you  
for your attention!