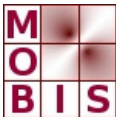


A Boundary Element Energy Approximation of Dirichlet Control Problems

G. Of T. Phan Xuan O. Steinbach

Institute of Computational Mathematics
Graz University of Technology

Workshop on PDE Constrained Optimization of Certain and Uncertain Processes 2009, 3.–5.6.2009



SFB Research Center: Mathematical Optimization and Applications in Biomedical Sciences
Subproject FEMBEM: Fast Finite Element and Boundary Element Methods for Optimality Systems

Outline

Dirichlet Boundary Control Problem

Boundary Integral Equations

Boundary Element Solution

Finite Element Approach

Numerical Results

Outline

Dirichlet Boundary Control Problem

Boundary Integral Equations

Boundary Element Solution

Finite Element Approach

Numerical Results

Dirichlet Boundary Control Problem

Model problem: Find $(u, z) \in H^1(\Omega) \times \mathcal{A}$ minimizing

$$J(u, z) = \frac{1}{2} \int_{\Omega} [u(x) - \bar{u}(x)]^2 dx + \frac{1}{2} \varrho \|z\|_{\mathcal{A}}^2$$

subject to the constraint

$$-\Delta u(x) = f(x) \quad \text{for } x \in \Omega, \quad u(x) = z(x) \quad \text{for } x \in \Gamma = \partial\Omega,$$

where

- ▶ given target $\bar{u} \in L_2(\Omega)$
- ▶ given volume density $f \in L_2(\Omega)$
- ▶ fixed parameter $\varrho \in \mathbb{R}_+$
- ▶ bounded Lipschitz domain $\Omega \subset \mathbb{R}^n$, $n = 2, 3$ with boundary $\Gamma = \partial\Omega$
- ▶ \mathcal{A} is a suitable operator to be chosen where $\|\cdot\|_{\mathcal{A}}^2 = \langle \mathcal{A}\cdot, \cdot \rangle_{\Gamma}$

Dirichlet Boundary Control Problem

Model problem: Find $(u, z) \in H^1(\Omega) \times \mathcal{A}$ minimizing

$$J(u, z) = \frac{1}{2} \int_{\Omega} [u(x) - \bar{u}(x)]^2 dx + \frac{1}{2} \varrho \|z\|_{\mathcal{A}}^2$$

subject to the constraint

$$-\Delta u(x) = f(x) \quad \text{for } x \in \Omega, \quad u(x) = z(x) \quad \text{for } x \in \Gamma = \partial\Omega,$$

where

- ▶ given target $\bar{u} \in L_2(\Omega)$
- ▶ given volume density $f \in L_2(\Omega)$
- ▶ fixed parameter $\varrho \in \mathbb{R}_+$
- ▶ bounded Lipschitz domain $\Omega \subset \mathbb{R}^n$, $n = 2, 3$ with boundary $\Gamma = \partial\Omega$
- ▶ \mathcal{A} is a suitable operator to be chosen where $\|\cdot\|_{\mathcal{A}}^2 = \langle \mathcal{A}\cdot, \cdot \rangle_{\Gamma}$
- ▶ $\mathcal{A} = L_2(\Omega)$: [Casas, Raymond 06], [May, Rannacher, Vexler 08], [Deckelnick, Günther, Hinze 08]

Solving the State Equation

Let $u_f \in H_0^1(\Omega)$ be the weak particular solution of

$$-\Delta u_f(x) = f(x) \quad \text{for } x \in \Omega, \quad u_f(x) = 0 \quad \text{for } x \in \Gamma.$$

Solving the State Equation

Let $u_f \in H_0^1(\Omega)$ be the weak particular solution of

$$-\Delta u_f(x) = f(x) \quad \text{for } x \in \Omega, \quad u_f(x) = 0 \quad \text{for } x \in \Gamma.$$

Let $u_z = Sz \in H^1(\Omega)$ be the weak solution of

$$-\Delta u_z(x) = 0 \quad \text{for } x \in \Omega, \quad u_z(x) = z(x) \quad \text{for } x \in \Gamma.$$

Solving the State Equation

Let $u_f \in H_0^1(\Omega)$ be the weak particular solution of

$$-\Delta u_f(x) = f(x) \quad \text{for } x \in \Omega, \quad u_f(x) = 0 \quad \text{for } x \in \Gamma.$$

Let $u_z = \mathcal{S}z \in H^1(\Omega)$ be the weak solution of

$$-\Delta u_z(x) = 0 \quad \text{for } x \in \Omega, \quad u_z(x) = z(x) \quad \text{for } x \in \Gamma.$$

$$u_z \in H^1(\Omega) \Rightarrow u_z|_{\Gamma} \in H^{1/2}(\Gamma) \Rightarrow \mathcal{S} : H^{1/2}(\Gamma) \rightarrow H^1(\Omega) \subset L_2(\Omega).$$

Solving the State Equation

Let $u_f \in H_0^1(\Omega)$ be the weak particular solution of

$$-\Delta u_f(x) = f(x) \quad \text{for } x \in \Omega, \quad u_f(x) = 0 \quad \text{for } x \in \Gamma.$$

Let $u_z = Sz \in H^1(\Omega)$ be the weak solution of

$$-\Delta u_z(x) = 0 \quad \text{for } x \in \Omega, \quad u_z(x) = z(x) \quad \text{for } x \in \Gamma.$$

$$u_z \in H^1(\Omega) \Rightarrow u_z|_{\Gamma} \in H^{1/2}(\Gamma) \Rightarrow S : H^{1/2}(\Gamma) \rightarrow H^1(\Omega) \subset L_2(\Omega).$$

Then the solution of the state equation

$$-\Delta u(x) = f(x) \quad \text{for } x \in \Omega, \quad u(x) = z(x) \quad \text{for } x \in \Gamma = \partial\Omega,$$

is given by

$$u = Sz + u_f.$$

Reduced Cost Functional

Using $u = Sz + u_f$: Find the minimizer $z \in H^{1/2}(\Gamma)$ of the **reduced cost functional**

$$\tilde{J}(z) = \frac{1}{2} \int_{\Omega} [(Sz)(x) + u_f(x) - \bar{u}(x)]^2 dx + \frac{1}{2} \varrho \langle Az, z \rangle_{\Gamma}.$$

$\tilde{J}(\cdot)$ is convex \Rightarrow minimizer z determined by **optimality condition**

$$S^* Sz + S^*(u_f - \bar{u}) + \varrho Az = 0.$$

$S^* : L_2(\Omega) \rightarrow H^{-1/2}(\Gamma)$ adjoint operator of $S : H^{1/2}(\Gamma) \rightarrow L_2(\Omega)$, i.e.,

$$\langle S^* \psi, \varphi \rangle_{\Gamma} = \langle \psi, S\varphi \rangle_{\Omega} = \int_{\Omega} \psi(x)(S\varphi)(x) dx \quad \text{for all } \varphi \in H^{1/2}(\Gamma), \psi \in L_2(\Omega).$$

Optimality system

Optimality condition: $\mathcal{S}^* \mathcal{S}z + \mathcal{S}^*(u_f - \bar{u}) + \varrho Az = 0.$

- ▶ primal variable $u = \mathcal{S}z + u_f$
- ▶ adjoint variable $\tau = \mathcal{S}^*(u - \bar{u}) \in H^{-1/2}(\Gamma),$

\Rightarrow coupled problem

$$\tau + \varrho Az = 0, \quad \tau = \mathcal{S}^*(u - \bar{u}), \quad u = \mathcal{S}z + u_f$$

Optimality system

Optimality condition: $\mathcal{S}^* \mathcal{S}z + \mathcal{S}^*(u_f - \bar{u}) + \varrho Az = 0.$

- ▶ primal variable $u = \mathcal{S}z + u_f$
- ▶ adjoint variable $\tau = \mathcal{S}^*(u - \bar{u}) \in H^{-1/2}(\Gamma),$

⇒ coupled problem

$$\tau + \varrho Az = 0, \quad \tau = \mathcal{S}^*(u - \bar{u}), \quad u = \mathcal{S}z + u_f$$

Adjoint variable $\tau = \mathcal{S}^*(u - \bar{u})$ is Neumann datum

$$\tau(x) = -\frac{\partial}{\partial n_x} p(x) \quad \text{for } x \in \Gamma$$

of the adjoint Dirichlet boundary value problem

$$-\Delta p(x) = u(x) - \bar{u}(x) \quad \text{for } x \in \Omega, \quad p(x) = 0 \quad \text{for } x \in \Gamma.$$

Optimality system

Optimality condition: $S^*S z + S^*(u_f - \bar{u}) + \varrho A z = 0$.

- ▶ primal variable $u = S z + u_f$
- ▶ adjoint variable $\tau = S^*(u - \bar{u}) \in H^{-1/2}(\Gamma)$,

⇒ coupled problem

$$\tau + \varrho A z = 0, \quad \tau = S^*(u - \bar{u}), \quad u = S z + u_f$$

Adjoint variable $\tau = S^*(u - \bar{u})$ is Neumann datum

$$\tau(x) = -\frac{\partial}{\partial n_x} p(x) \quad \text{for } x \in \Gamma$$

of the adjoint Dirichlet boundary value problem

$$-\Delta p(x) = u(x) - \bar{u}(x) \quad \text{for } x \in \Omega, \quad p(x) = 0 \quad \text{for } x \in \Gamma.$$

⇒ optimality condition: $\frac{\partial}{\partial n_x} p(x) = \varrho(Az)(x) \quad \text{for } x \in \Gamma$.

Choosing \mathcal{A} and $\|\cdot\|_{\mathcal{A}}$

Optimality condition: $\frac{\partial}{\partial n_x} p(x) = \varrho(Az)(x) \quad \text{for } x \in \Gamma.$

$$u \in H^1(\Omega) \Rightarrow u|_{\Gamma} = z \in H^{1/2}(\Gamma)$$

→ elliptic, self-adjoint, and bounded operator $A : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma),$

Choosing \mathcal{A} and $\|\cdot\|_{\mathcal{A}}$

Optimality condition: $\frac{\partial}{\partial n_x} p(x) = \varrho(Az)(x) \quad \text{for } x \in \Gamma.$

$$u \in H^1(\Omega) \Rightarrow u|_{\Gamma} = z \in H^{1/2}(\Gamma)$$

→ elliptic, self-adjoint, and bounded operator $A : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$,
 e.g., the stabilized hypersingular boundary integral operator $A = \tilde{D}$

$$\langle \tilde{D}z, w \rangle_{\Gamma} := \langle Dz, w \rangle_{\Gamma} + \langle z, 1 \rangle_{\Gamma} \langle w, 1 \rangle_{\Gamma} \quad \text{for all } z, w \in H^{1/2}(\Gamma)$$

where

$$(Dz)(x) = -\frac{\partial}{\partial n_x} \int_{\Gamma} \frac{\partial}{\partial n_y} U^*(x, y) z(y) ds_y \quad \text{for } x \in \Gamma,$$

and the fundamental solution

$$U^*(x, y) = \begin{cases} -\frac{1}{2\pi} \log |x - y| & \text{for } n = 2, \\ \frac{1}{4\pi} \frac{1}{|x - y|} & \text{for } n = 3 \end{cases}$$

Unique Solvability and Regularity

Theorem

Let $A : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ be elliptic, self-adjoint, and bounded.
 The operator $T_\varrho = \varrho A + \mathcal{S}^* \mathcal{S} : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ is bounded and $H^{1/2}(\Gamma)$ -elliptic. \Rightarrow *unique solvability of*

$$T_\varrho z := (\mathcal{S}^* \mathcal{S} + \varrho A)z = \mathcal{S}^*(\bar{u} - u_f) =: g.$$

Unique Solvability and Regularity

Theorem

Let $A : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ be elliptic, self-adjoint, and bounded.
 The operator $T_\varrho = \varrho A + S^* S : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ is bounded and $H^{1/2}(\Gamma)$ -elliptic. \Rightarrow unique solvability of

$$T_\varrho z := (S^* S + \varrho A)z = S^*(\bar{u} - u_f) =: g.$$

Optimality system

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega, & u &= z && \text{on } \Gamma, \\ -\Delta p &= u - \bar{u} && \text{in } \Omega, & p &= 0 && \text{on } \Gamma, \\ \frac{\partial}{\partial n_x} p &= \varrho A z && \text{on } \Gamma. \end{aligned}$$

Regularity:

If Γ smooth and $u - \bar{u} \in H^s(\Omega)$: $\Rightarrow p \in H^{s+2}(\Omega) \Rightarrow \frac{\partial}{\partial n} p \in H^{s+1/2}(\Gamma)$

Unique Solvability and Regularity

Theorem

Let $A : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ be elliptic, self-adjoint, and bounded.
 The operator $T_\varrho = \varrho A + S^* S : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ is bounded and $H^{1/2}(\Gamma)$ -elliptic. \Rightarrow unique solvability of

$$T_\varrho z := (S^* S + \varrho A)z = S^*(\bar{u} - u_f) =: g.$$

Optimality system

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega, & u &= z && \text{on } \Gamma, \\ -\Delta p &= u - \bar{u} && \text{in } \Omega, & p &= 0 && \text{on } \Gamma, \\ \frac{\partial}{\partial n_x} p &= \varrho A z && \text{on } \Gamma. \end{aligned}$$

Regularity:

If Γ smooth and $u - \bar{u} \in H^s(\Omega)$: $\Rightarrow p \in H^{s+2}(\Omega) \Rightarrow \frac{\partial}{\partial n} p \in H^{s+1/2}(\Gamma)$

By $A : H^{s+1/2}(\Gamma) \rightarrow H^{s+3/2}(\Gamma)$: $z \in H^{s+3/2}(\Gamma) \Rightarrow u \in H^{s+2}(\Omega)$.

Unique Solvability and Regularity

Theorem

Let $A : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ be elliptic, self-adjoint, and bounded.
 The operator $T_\varrho = \varrho A + S^* S : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ is bounded and $H^{1/2}(\Gamma)$ -elliptic. \Rightarrow unique solvability of

$$T_\varrho z := (S^* S + \varrho A)z = S^*(\bar{u} - u_f) =: g.$$

Optimality system

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega, & u &= z && \text{on } \Gamma, \\ -\Delta p &= u - \bar{u} && \text{in } \Omega, & p &= 0 && \text{on } \Gamma, \\ \frac{\partial}{\partial n_x} p &= \varrho A z && \text{on } \Gamma. \end{aligned}$$

Regularity:

If Γ smooth and $u - \bar{u} \in H^s(\Omega)$: $\Rightarrow p \in H^{s+2}(\Omega) \Rightarrow \frac{\partial}{\partial n} p \in H^{s+1/2}(\Gamma)$

By $A : H^{s+1/2}(\Gamma) \rightarrow H^{s+3/2}(\Gamma)$: $z \in H^{s+3/2}(\Gamma) \Rightarrow u \in H^{s+2}(\Omega)$.

If Γ piecewise polygonal: reduced regularity.

Outline

Dirichlet Boundary Control Problem

Boundary Integral Equations

Boundary Element Solution

Finite Element Approach

Numerical Results

Primal Boundary Value Problem

$$-\Delta u(x) = f(x) \quad \text{for } x \in \Omega, \quad u(x) = z(x) \quad \text{for } x \in \Gamma$$

Its solution is given by the **representation formula** for $\tilde{x} \in \Omega$,

$$u(\tilde{x}) = \int_{\Gamma} U^*(\tilde{x}, y) \frac{\partial}{\partial n_y} u(y) ds_y - \int_{\Gamma} \frac{\partial}{\partial n_y} U^*(\tilde{x}, y) z(y) ds_y + \int_{\Omega} U^*(\tilde{x}, y) f(y) dy,$$

Primal Boundary Value Problem

$$-\Delta u(x) = f(x) \quad \text{for } x \in \Omega, \quad u(x) = z(x) \quad \text{for } x \in \Gamma$$

Its solution is given by the **representation formula** for $\tilde{x} \in \Omega$,

$$u(\tilde{x}) = \int_{\Gamma} U^*(\tilde{x}, y) \frac{\partial}{\partial n_y} u(y) ds_y - \int_{\Gamma} \frac{\partial}{\partial n_y} U^*(\tilde{x}, y) z(y) ds_y + \int_{\Omega} U^*(\tilde{x}, y) f(y) dy,$$

For given $z \in H^{1/2}(\Gamma)$, we determine $t = \frac{\partial}{\partial n} u \in H^{-1/2}(\Gamma)$ by

$$(Vt)(x) = \left(\frac{1}{2}I + K\right)z(x) - (N_0f)(x) \quad \text{for } x \in \Gamma.$$

where

$$(Vt)(x) = \int_{\Gamma} U^*(x, y)t(y) ds_y \quad (Kz)(x) = \int_{\Gamma} \frac{\partial}{\partial n_y} U^*(x, y)z(y) ds_y$$

$$(N_0f)(x) = \int_{\Omega} U^*(x, y)f(y) dy \quad \text{for } x \in \Gamma$$

Adjoint Boundary Value Problem

$$-\Delta p(x) = u(x) - \bar{u}(x) \quad \text{for } x \in \Omega, \quad p(x) = 0 \quad \text{for } x \in \Gamma,$$

We obtain the unknown Neumann datum $q = \frac{\partial}{\partial n} p$ by

$$(Vq)(x) = (N_0 \bar{u})(x) - (N_0 u)(x) \quad \text{for } x \in \Gamma$$

BUT: Unknown u occurs in domain potential.

Adjoint Boundary Value Problem

$$-\Delta p(x) = u(x) - \bar{u}(x) \quad \text{for } x \in \Omega, \quad p(x) = 0 \quad \text{for } x \in \Gamma,$$

We obtain the unknown Neumann datum $q = \frac{\partial}{\partial n} p$ by

$$(Vq)(x) = (N_0 \bar{u})(x) - (N_0 u)(x) \quad \text{for } x \in \Gamma$$

BUT: Unknown u occurs in domain potential.

Remedy: integration by parts ($-\Delta u = f$) to end up with a system of boundary integral equations only:

$$\begin{aligned} \int_{\Omega} U^*(\tilde{x}, y) u(y) dy &= \int_{\Omega} [\Delta_y V^*(\tilde{x}, y)] u(y) dy \\ &= \int_{\Gamma} \frac{\partial}{\partial n_y} V^*(\tilde{x}, y) u(y) ds_y - \int_{\Gamma} V^*(\tilde{x}, y) \frac{\partial}{\partial n_y} u(y) ds_y + \int_{\Omega} V^*(\tilde{x}, y) [\Delta u(y)] dy \end{aligned}$$

where $V^*(x, y)$ is a is the fundamental solution of the Bi-Laplacian.

Adjoint Boundary Value Problem

Therefore we get

$$(Vq)(x) = (V_1t)(x) - (K_1z)(x) + (N_0\bar{u})(x) + (M_0f)(x) \quad \text{for } x \in \Gamma.$$

where

$$(V_1t)(x) = \int_{\Gamma} V^*(x, y)t(y)ds_y \quad (K_1z)(x) = \int_{\Gamma} \frac{\partial}{\partial n_y} V^*(x, y)z(y)ds_y$$

$$(M_0f)(x) = \int_{\Omega} V^*(x, y)f(y)dy \quad \text{for } x \in \Gamma$$

are integral operators of the bi-harmonic equation.

Optimality Condition

To obtain a **symmetric system**, we rewrite $q(x) = \frac{\partial}{\partial n} p(x)$ by integral operators

$$q(x) = \left(\frac{1}{2}I + K'\right)q(x) - (D_1 z)(x) - (K_1' t)(x) - (N_1 \bar{u})(x) - (M_1 f)(x)$$

where $(x \in \Gamma)$

$$(N_1 \bar{u})(x) = \lim_{\Omega \ni \tilde{x} \rightarrow x \in \Gamma} n_x \cdot \nabla_{\tilde{x}} \int_{\Omega} U^*(\tilde{x}, y) \bar{u}(y) dy$$

$$(M_1 f)(x) = \lim_{\Omega \ni \tilde{x} \rightarrow x \in \Gamma} n_x \cdot \nabla_{\tilde{x}} \int_{\Omega} V^*(\tilde{x}, y) f(y) dy$$

Optimality Condition

To obtain a **symmetric system**, we rewrite $q(x) = \frac{\partial}{\partial n} p(x)$ by integral operators

$$q(x) = \left(\frac{1}{2}I + K'\right)q(x) - (D_1z)(x) - (K_1't)(x) - (N_1\bar{u})(x) - (M_1f)(x)$$

where $(x \in \Gamma)$

$$(N_1\bar{u})(x) = \lim_{\Omega \ni \tilde{x} \rightarrow x \in \Gamma} n_x \cdot \nabla_{\tilde{x}} \int_{\Omega} U^*(\tilde{x}, y) \bar{u}(y) dy$$

$$(M_1f)(x) = \lim_{\Omega \ni \tilde{x} \rightarrow x \in \Gamma} n_x \cdot \nabla_{\tilde{x}} \int_{\Omega} V^*(\tilde{x}, y) f(y) dy$$

Inserted into the optimality condition:

$$\varrho(Az)(x) = \left(\frac{1}{2}I + K'\right)q(x) - (D_1z)(x) - (K_1't)(x) - (N_1\bar{u})(x) - (M_1f)(x).$$

Coupled System

Find $(z, t, q) \in H^{1/2}(\Gamma) \times H^{-1/2}(\Gamma) \times H^{-1/2}(\Gamma)$:

$$\begin{pmatrix} -V_1 & V & K_1 \\ V & -\frac{1}{2}I - K & \\ K_1' & -\frac{1}{2}I - K' & \rho A + D_1 \end{pmatrix} \begin{pmatrix} t \\ q \\ z \end{pmatrix} = \begin{pmatrix} N_0 \bar{u} + M_0 f \\ -N_0 f \\ -N_1 \bar{u} - M_1 f \end{pmatrix}.$$

Coupled System

Find $(z, t, q) \in H^{1/2}(\Gamma) \times H^{-1/2}(\Gamma) \times H^{-1/2}(\Gamma)$:

$$\begin{pmatrix} -V_1 & V & K_1 \\ V & -\frac{1}{2}I - K' & -\frac{1}{2}I - K \\ K_1' & -\frac{1}{2}I - K' & \varrho A + D_1 \end{pmatrix} \begin{pmatrix} t \\ q \\ z \end{pmatrix} = \begin{pmatrix} N_0 \bar{u} + M_0 f \\ -N_0 f \\ -N_1 \bar{u} - M_1 f \end{pmatrix}.$$

The Schur complement system is **uniquely solvable**

$$T_\varrho z = g.$$

Theorem

Let $A : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma)$ be elliptic, self-adjoint, and bounded.
The composed boundary integral operator

$$T_\varrho = \varrho A + D_1 - \left(\frac{1}{2}I + K'\right)V^{-1}V_1V^{-1}\left(\frac{1}{2}I + K\right) + K_1'V^{-1}\left(\frac{1}{2}I + K\right) + \left(\frac{1}{2}I + K'\right)V^{-1}K_1$$

is self-adjoint, bounded, and $H^{1/2}(\Gamma)$ -elliptic.

Outline

Dirichlet Boundary Control Problem

Boundary Integral Equations

Boundary Element Solution

Finite Element Approach

Numerical Results

Galerkin Boundary Element Formulation

Approximate

- ▶ t by piecewise constant basis functions ψ_k
- ▶ q by piecewise constant basis functions ψ_k
- ▶ z by piecewise linear basis functions φ_i

Galerkin Boundary Element Formulation

Approximate

- ▶ t by piecewise constant basis functions ψ_k
- ▶ q by piecewise constant basis functions ψ_k
- ▶ z by piecewise linear basis functions φ_i

System of linear equations:

$$\begin{pmatrix} -V_{1,h} & V_h & K_{1,h} \\ V_h & -(\frac{1}{2}M_h + K_h) & \\ K_{1,h}^\top & -(\frac{1}{2}M_h^\top + K_h^\top) & \varrho A_h + D_{1,h} \end{pmatrix} \begin{pmatrix} \underline{t} \\ \underline{q} \\ \underline{z} \end{pmatrix} = \begin{pmatrix} \underline{f}_1 \\ \underline{f}_2 \\ \underline{f}_3 \end{pmatrix}$$

Galerkin Boundary Element Formulation

Approximate

- ▶ t by piecewise constant basis functions ψ_k
- ▶ q by piecewise constant basis functions ψ_k
- ▶ z by piecewise linear basis functions φ_i

System of linear equations:

$$\begin{pmatrix} -V_{1,h} & V_h & K_{1,h} \\ V_h & -(\frac{1}{2}M_h + K_h) & \\ K_{1,h}^\top & -(\frac{1}{2}M_h^\top + K_h^\top) & \varrho A_h + D_{1,h} \end{pmatrix} \begin{pmatrix} \underline{t} \\ \underline{q} \\ \underline{z} \end{pmatrix} = \begin{pmatrix} \underline{f}_1 \\ \underline{f}_2 \\ \underline{f}_3 \end{pmatrix}$$

Schur complement system:

$$T_{\varrho,h} \underline{z} = \underline{f},$$

Lemma

$T_{\varrho,h}$ is positive definite, i.e.,

$$(T_{\varrho,h} \underline{z}, \underline{z}) \geq \varrho (A_h \underline{z}, \underline{z}) = \varrho \langle A z_h, z_h \rangle_\Gamma \geq \varrho \gamma_1^A \|z_h\|_{H^{1/2}(\Gamma)}^2$$

for all $\underline{z} \in \mathbb{R}^M \leftrightarrow z_h \in S_h^1(\Gamma)$.

Error Estimates

Theorem

Let $z \in H^{1/2}(\Gamma)$ be the unique solution of the optimality system. Let $z_h \in S_h^1(\Gamma)$ be the unique solution of BEM system. Then there holds the error estimate

$$\|z - z_h\|_{H^{1/2}(\Gamma)} \leq c(z, \bar{u}, f) h^{3/2},$$

when assuming $u \in H^{5/2}(\Omega)$, $z \in H^2(\Gamma)$, and $t_z \in H_{pw}^1(\Gamma)$.

Error Estimates

Theorem

Let $z \in H^{1/2}(\Gamma)$ be the unique solution of the optimality system. Let $z_h \in S_h^1(\Gamma)$ be the unique solution of BEM system. Then there holds the error estimate

$$\|z - z_h\|_{H^{1/2}(\Gamma)} \leq c(z, \bar{u}, f) h^{3/2},$$

when assuming $u \in H^{5/2}(\Omega)$, $z \in H^2(\Gamma)$, and $t_z \in H_{pw}^1(\Gamma)$. By Aubin–Nitsche trick:

$$\|z - z_h\|_{L_2(\Gamma)} \leq c(z, \bar{u}, f) h^2.$$

Error Estimates

Theorem

Let $z \in H^{1/2}(\Gamma)$ be the unique solution of the optimality system. Let $z_h \in S_h^1(\Gamma)$ be the unique solution of BEM system. Then there holds the error estimate

$$\|z - z_h\|_{H^{1/2}(\Gamma)} \leq c(z, \bar{u}, f) h^{3/2},$$

when assuming $u \in H^{5/2}(\Omega)$, $z \in H^2(\Gamma)$, and $t_z \in H_{pw}^1(\Gamma)$. By Aubin–Nitsche trick:

$$\|z - z_h\|_{L_2(\Gamma)} \leq c(z, \bar{u}, f) h^2.$$

Remark:

- ▶ estimate hold for smooth Γ
- ▶ reduced order of convergence for Γ piecewise polygonal

Outline

Dirichlet Boundary Control Problem

Boundary Integral Equations

Boundary Element Solution

Finite Element Approach

Numerical Results

Finite Element Approximation

System

$$\begin{aligned}
 -\Delta p &= u - \bar{u} & \text{in } \Omega, & & p=0 & \text{ on } \Gamma, \\
 -\Delta u &= f & \text{in } \Omega, & & u=z & \text{ on } \Gamma, \\
 \frac{\partial}{\partial n_x} p &= \varrho A z & \text{on } \Gamma & & & .
 \end{aligned}$$

FE discretization:

$$\begin{pmatrix} -M_{II} & K_{II} & -M_{CI} \\ K_{II} & & K_{CI} \\ M_{IC} & -K_{IC} & M_{CC} + \varrho A_h \end{pmatrix} \begin{pmatrix} \underline{u}_I \\ \underline{p} \\ \underline{z} \end{pmatrix} = \begin{pmatrix} -\underline{g}_I \\ \underline{f}_I \\ \underline{g}_C \end{pmatrix}.$$

Finite Element Approximation

System

$$\begin{aligned}
 -\Delta p &= u - \bar{u} & \text{in } \Omega, & \quad p=0 & \text{on } \Gamma, \\
 -\Delta u &= f & \text{in } \Omega, & \quad u=z & \text{on } \Gamma, \\
 \frac{\partial}{\partial n_x} p &= \varrho Az & \text{on } \Gamma & \quad .
 \end{aligned}$$

FE discretization:

$$\begin{pmatrix} -M_{II} & K_{II} & -M_{CI} \\ K_{II} & & K_{CI} \\ M_{IC} & -K_{IC} & M_{CC} + \varrho A_h \end{pmatrix} \begin{pmatrix} \underline{u}_I \\ \underline{p} \\ \underline{z} \end{pmatrix} = \begin{pmatrix} -\underline{g}_I \\ \underline{f}_I \\ \underline{g}_C \end{pmatrix}.$$

BE discretization:

$$\begin{pmatrix} -V_{1,h} & V_h & K_{1,h} \\ V_h & & -(\frac{1}{2}M_h + K_h) \\ K_{1,h}^\top & -(\frac{1}{2}M_h^\top + K_h^\top) & \varrho A_h + D_{1,h} \end{pmatrix} \begin{pmatrix} \underline{t} \\ \underline{q} \\ \underline{z} \end{pmatrix} = \begin{pmatrix} \underline{f}_1 \\ \underline{f}_2 \\ \underline{f}_3 \end{pmatrix}$$

Finite Element Approximation

FE discretization:

$$\begin{pmatrix} -M_{II} & K_{II} & -M_{CI} \\ K_{II} & & K_{CI} \\ M_{IC} & -K_{IC} & M_{CC} + \varrho A_h \end{pmatrix} \begin{pmatrix} \underline{u}_I \\ \underline{p} \\ \underline{z} \end{pmatrix} = \begin{pmatrix} -\underline{g}_I \\ \underline{f}_I \\ \underline{g}_C \end{pmatrix}.$$

Lemma

The Schur complement matrix

$$\tilde{T}_{\varrho,h} = K_{IC}K_{II}^{-1}M_{II}K_{II}^{-1}K_{CI} - K_{IC}K_{II}^{-1}M_{CI} - M_{IC}K_{II}^{-1}K_{CI} + M_{CC} + \varrho A_h$$

is *positive definite*.

Finite Element Approximation

FE discretization:

$$\begin{pmatrix} -M_{II} & K_{II} & -M_{CI} \\ K_{II} & & K_{CI} \\ M_{IC} & -K_{IC} & M_{CC} + \varrho A_h \end{pmatrix} \begin{pmatrix} \underline{u}_I \\ \underline{p} \\ \underline{z} \end{pmatrix} = \begin{pmatrix} -\underline{g}_I \\ \underline{f}_I \\ \underline{g}_C \end{pmatrix}.$$

Lemma

The Schur complement matrix

$$\tilde{T}_{\varrho,h} = K_{IC}K_{II}^{-1}M_{II}K_{II}^{-1}K_{CI} - K_{IC}K_{II}^{-1}M_{CI} - M_{IC}K_{II}^{-1}K_{CI} + M_{CC} + \varrho A_h$$

is *positive definite*.

Theorem

Error estimates of the FE approximations:

$$\|z - z_h\|_{H^{1/2}(\Gamma)} \leq c(z, \bar{u}, f) h \quad \|u - u_h\|_{H^1(\Omega)} \leq c(z, \bar{u}, f) h$$

$$\|z - z_h\|_{L_2(\Gamma)} \leq c(z, \bar{u}, f) h^{3/2} \quad \|u - u_h\|_{L_2(\Omega)} \leq c(z, \bar{u}, f) h^2$$

Outline

Dirichlet Boundary Control Problem

Boundary Integral Equations

Boundary Element Solution

Finite Element Approach

Numerical Results

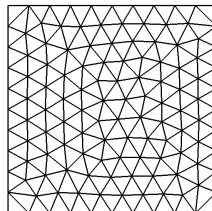
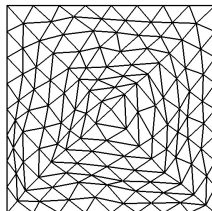
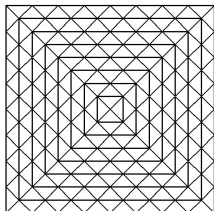
Numerical example: BEM and BEM

domain $\Omega = (0, \frac{1}{2})^2 \subset \mathbb{R}^2$, uniform mesh,

$$\bar{u}(x) = - \left(4 + \frac{1}{\varrho} \right) [x_1(1 - 2x_1) + x_2(1 - 2x_2)], \quad f(x) = -\frac{8}{\varrho}, \quad \varrho = 0.01.$$

	BEM		FEM		FEM, L_2	
L	$\ z_L - z_9^B\ $	eoc	$\ z_L - z_9^F\ $	eoc	$\ z_L - z\ $	eoc
2	2.25e-0		3.89e-1		4.50e-01	
3	4.66e-1	2.27	1.07e-1	1.86	1.77e-01	1.35
4	8.84e-2	2.39	2.81e-2	1.93	7.94e-02	1.15
5	1.63e-2	2.44	7.28e-3	1.95	3.38e-02	1.23
6	3.02e-3	2.43	1.87e-3	1.96	1.34e-02	1.34
7	5.73e-4	2.40	4.69e-4	2.00	5.02e-03	1.41
8	1.24e-4	2.20	1.06e-4	2.15	1.83e-03	1.45

Numerical example: FEM several meshes



L	N	$\ z_L - z_9^F\ $	eoc	$\ z_L - z_9^F\ $	eoc	N	$\ z_L - z_9^F\ $	eoc
3	256	1.07e-01		1.25e-01		216	1.65e-01	
4	1024	2.81e-02	1.94	3.26e-02	1.94	864	4.69e-02	1.81
5	4096	7.28e-03	1.95	8.45e-03	1.95	3456	1.29e-02	1.87
6	16384	1.87e-03	1.96	2.17e-03	1.96	13824	3.39e-03	1.93
7	65536	4.69e-04	2.00	5.43e-04	2.00	55296	8.41e-04	2.01
8	262144	1.06e-04	2.15	1.20e-04	2.18	221184	1.76e-04	2.26

Numerical example: \bar{u} singular

domain $\Omega = (0, \frac{1}{2})^2 \subset \mathbb{R}^2$, uniform mesh,

$$\bar{u} = (x_1^2 + x_2^2)^{-1/3}, \quad f = 0, \quad \varrho = 0.01$$

L	N	BEM		FEM		FEM216		
		$\ z_L - z_9^B\ $	eoc	$\ z_L - z_9^B\ $	eoc	N	$\ z_L - z_9^F\ $	eoc
3	256	7.00e-2		3.61e-02		216	9.74e-02	
4	1024	2.13e-2	1.71	1.55e-02	1.22	864	4.10e-02	1.25
5	4096	6.46e-3	1.72	5.88e-03	1.40	3456	1.52e-02	1.43
6	16384	1.94e-3	1.74	2.08e-03	1.50	13824	5.18e-03	1.55
7	65536	5.67e-4	1.77	6.88e-04	1.60	55296	1.62e-03	1.67
8	262144	1.54e-4	1.88	1.91e-04	1.85	221184	4.19e-04	1.95

Outlook

- ▶ partial Dirichlet boundary control
- ▶ BEM
- ▶ box constraints
- ▶ time dependent problems
- ▶ fast solvers